# Formal Language Constrained Reachability and Model Checking Propositional Dynamic Logics

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# Reachability Problems

## reachability problems have two parameters:

- structures: where to find connection finite graphs, pushdown graphs, Petri nets, ...
- objectives: what kind of connection classes of formal languages

	finite	infinite	
regular	easy	lots of work	
non-regular	here	quickly undecidable	

### **Motivation**

## Question

Given a finite, directed,  $\Sigma$ -edge-labeled graph  $G = (V, \rightarrow)$  and  $s, t \in V$ .

Is it possible to decide effectively whether there is a path from s to t of the form

- $a^n b^n c^n$  for some  $n \in \mathbb{N}$ ?
- ww for some  $w \in \Sigma^*$ ?

Is it possible efficiently?

#### **Outline**

- definition of three decision problems from
  - reachability theory
  - formal language theory
  - model checking
- interreducibility
- consequences

# Formal Language Constrained Reachability

finite, directed graphs with edge labels from finite set  $\Sigma$ :  $G = (V, \rightarrow)$  with  $\rightarrow \subseteq V \times \Sigma \times V$ 

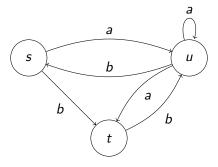
edge relation extends to words  $w \in \Sigma^*$  inductively:

$$s \xrightarrow{\epsilon} t \quad \text{iff} \quad s = t$$
$$s \xrightarrow{aw} t \quad \text{iff} \quad \exists u.s \xrightarrow{a} u \land u \xrightarrow{w} t$$

# Definition 1 (Formal Language Constrained Reachability)

Given  $G = (V, \rightarrow)$ ,  $s \in V$ ,  $T \subseteq V$ , and  $L \subseteq \Sigma^*$ , decide whether or not there is  $t \in T$  and  $w \in L$  s.t.  $s \xrightarrow{w} t$ .

## **Example**



is  $\{t\}$  reachable from s via  $\{a^nb^n\mid n\in\mathbb{N}\}$ ? yes, e.g. via  $s\xrightarrow{a}u\xrightarrow{a}u\xrightarrow{a}t\xrightarrow{b}u\xrightarrow{b}s\xrightarrow{b}t$ 

# **Regular Intersection**

# Definition 2 (Regular Intersection)

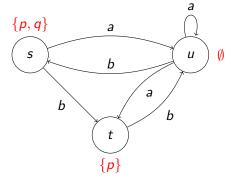
Given a formal language  $L \subseteq \Sigma^*$  and an NFA for a regular language  $R \subseteq \Sigma^*$  decide whether or not  $L \cap R \neq \emptyset$ 

## Remark

Let  $\mathcal{C} \subseteq 2^{\Sigma^*}$ . If  $\mathcal{C}$  closed under intersections with regular languages and has decidable emptiness problem then regular intersection is decidable too.

## Model Checking PDL

PDL = modal logic interpreted over directed, edge-  $(\Sigma)$  and node-labeled  $(2^{\mathcal{P}})$  graphs with accessibility relations closed under compositions and including tests



## **Syntax and Semantics**

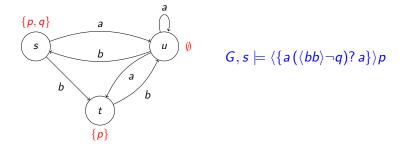
syntax defines formulas and programs inductively:

- $\mathcal{P} \subseteq FORM$
- $\varphi, \psi \in \text{Form} \Longrightarrow \varphi \lor \psi, \neg \varphi \in \text{Form}$
- $\varphi \in \text{FORM} \text{ and } L \subseteq \text{PROG}^* \Longrightarrow \langle L \rangle \varphi \in \text{FORM}$
- $\Sigma \subseteq PROG$
- $\varphi \in \text{Form} \Longrightarrow \varphi? \in \text{Prog}$

#### semantics:

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s \xrightarrow{\varphi?} t \quad \text{iff} \quad s = t \text{ and } s \models \varphi
G, s \models \langle L \rangle \varphi \quad \text{iff} \quad \exists t. \exists w \in L. s \xrightarrow{w} t \text{ and } t \models \varphi
\vdots
```

## **Example**



# Definition 3 (Model Checking PDL)

Given  $G = (V, \rightarrow, \lambda)$ ,  $s \in V$  and  $\varphi \in FORM$ , decide whether or not  $s \models \varphi$  holds.

#### **Parametrisation**

goal: determine complexity and decidability of these three problems answers clearly depend on classes of languages being used formally consider problems parametrised by class  $\mathcal C$  of formal languages

- Reach[ $\mathcal{C}$ ]: reachability problem for finite digraphs and objectives  $\mathcal{C}$
- $\operatorname{REGISECT}[\mathcal{C}]$ : regular intersection problem for  $\mathcal{C}$
- ullet MC-PDL[ $\mathcal C$ ]: model checking for PDL over languages from  $\mathcal C$

#### Reductions

## Theorem 4

- a) REACH[ $\mathcal{C}$ ]  $\equiv_{\text{lin}}$  REGISECT[ $\mathcal{C}$ ]
- b) Reach[ $\mathcal{C}$ ]  $\leq_{\text{lin}}$  MC-PDL[ $\mathcal{C}$ ]
- c) MC-PDL[ $\mathcal{C}$ ]  $\leq_{\mathcal{O}(n^2)}^{\text{Turing}}$  Reach[ $\mathcal{C}$ ]

proof quite simple

benefit: transfers results from formal language theory to reachability and model checking

#### Reductions

# (a) Reach[C] $\leq$ ReglSect[C]

given 
$$G = (V, \rightarrow)$$
,  $s$ ,  $T$  and  $L \in \mathcal{C}$ , take NFA  $\mathcal{A} = (V, s, \rightarrow, T)$   
 $s \xrightarrow{w} t$  for some  $w \in L \iff L \cap L(\mathcal{A}) \neq \emptyset$ 

# $\mathsf{ReglSect}[\mathcal{C}] \leq \mathsf{Reach}[\mathcal{C}]$

analogously

# (b) Reach[C] $\leq$ MC-PDL[C]

given 
$$G=(V,\to)$$
,  $s$ ,  $T$  and  $L\in\mathcal{C}$ , take  $G'=(V,\to,\lambda)$  with  $q_T\in\lambda(t)$  iff  $t\in T$ 

$$s \xrightarrow{w} t$$
 for some  $w \in L \iff G', s \models \langle L \rangle q_T$ 

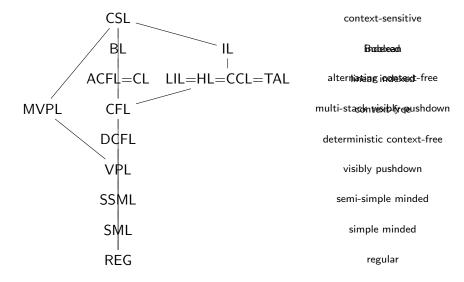
#### Reductions

# (c) MC-PDL[C] $\leq$ <sup>Turing</sup> Reach[C]

model checking algorithm for  $\mathsf{PDL}[\mathcal{C}]$  with oracle for  $\mathsf{REACH}[\mathcal{C}]$ 

$$\begin{array}{ll} \operatorname{MC}(\varphi, G = (V, \to, \lambda)) = \\ \operatorname{case} \ \varphi \ \operatorname{of} \\ q & : \ \operatorname{return} \ \{v \mid q \in \lambda(v)\} \\ \psi_1 \lor \psi_2 : \ \operatorname{return} \ \operatorname{MC}(\psi_1, G) \cup \operatorname{MC}(\psi_2, G) \\ \neg \psi & : \ \operatorname{return} \ V \setminus \operatorname{MC}(\psi, G) \\ \langle L \rangle \psi & : \ \operatorname{let} \ \Phi \ \operatorname{be} \ \operatorname{top-level} \ \operatorname{test} \ \operatorname{formulas} \ \operatorname{used} \ \operatorname{in} \ L \\ \to' := \left\{(v, \vartheta?, v) \mid \vartheta \in \Phi, v \in \operatorname{MC}(\vartheta, G)\right\} \\ G' := (V, \to \cup \to', \lambda) \\ T := \operatorname{MC}(\psi, G') \\ \operatorname{return} \ \left\{v \in V \mid (v, T) \in \operatorname{Reach}(L)\right\} \end{array}$$

# **Classes of Formal Languages**



## The Picture Now

language class ${\cal C}$	RegiSect[C]	Reach[C]	$\mathrm{MC} ext{-}\mathrm{PDL}[\mathcal{C}]$
ACFL,CL,BL, <b>CSL</b>	undec. [Landweber'63]	undec. [Barrett et al.'00]	undec.
MVPL	2EXPTIME [LaTorre et al.'07, Atig et al.'08]	2EXPTIME	
IL	EXPTIME [Aho'68, Tanaka/Kasai'07]	EXPTIME	
LIL,HL,CCL,TAL	PTIME [Gazdar'88],↓	PTIME	
DCFL, <b>CFL</b>	PTIME [Bar-Hillel et al.'61],↓	PTIME [Barrett et al.'00], ↓	PTIME [Lange'05],↓
SML, SSML, VPL	PTIME ↑,[Lange'11]		
REG	NLOGSPACE [Hunt'73]		PTIME [Fischer/Ladner'79, folk.]

# **Re-Consider Introductory Questions**

## Question

Given a finite, directed,  $\Sigma$ -edge-labeled graph  $G = (V, \rightarrow)$  and  $s, t \in V$ .

Is it possible to decide effectively whether there is a path from s to t of the form

•  $a^n b^n c^n$  for some  $n \in \mathbb{N}$ ?

**yes**∈ PTIME

• ww for some  $w \in \Sigma^*$ ?

yes∈ EXPTIME

Is it possible efficiently?

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\{ww \mid w \in \Sigma^*\} is an indexed language (IL) \{a^nb^nc^n \mid n \in \mathbb{N}\} is a linear indexed language (LIL)
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